Motivation and examples for $\infty\text{-categories}$

Neil Strickland

February 22, 2023

- For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \to X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \to X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow Sp$ correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow \text{Sp}$ correspond to X-parametrised spectra.

Let X be a topological space.

For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \to X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$

Try to make P_X into a category with composition given by joining paths.

- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow \text{Sp}$ correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow \text{Sp}$ correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- Problem: generalise so that (something like) P_X counts as an ∞ -category.
- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

Let X be a topological space.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)

▶ Problem: generalise so that (something like) P_X counts as an ∞-category.

- **•** This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- ▶ Problem: generalise so that (something like) P_X counts as an ∞-category.
- ▶ This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- ▶ Problem: generalise so that (something like) P_X counts as an ∞-category.
- This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- ▶ For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \rightarrow X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- ▶ Problem: generalise so that (something like) P_X counts as an ∞-category.
- This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

Let X be a topological space.

- ► For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \to X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- ▶ Problem: generalise so that (something like) P_X counts as an ∞-category.
- This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.

Similarly: ∞ -functors $P_X \rightarrow$ Sp correspond to X-parametrised spectra.

- ► For $a, b \in X$ put $P_X(a, b) = \{ \text{paths } u : [0, 1] \to X \text{ from } a \text{ to } b \}$ and $\Pi_X(a, b) = \pi_0(P_X(a, b)) = \{ \text{ pinned homotopy classes of paths } \}.$
- Try to make P_X into a category with composition given by joining paths.
- This does not work because path join is only associative up to pinned homotopy. However, Π_X becomes a category. (In fact, a groupoid.)
- ▶ Problem: generalise so that (something like) P_X counts as an ∞-category.
- This can be done, and we get: Spaces $\simeq \infty$ -groupoids \simeq Kan complexes.
- ► This is one reason why ∞-categories are an excellent framework for homotopy theory.
- ▶ Recall: functors $\Pi_X \rightarrow$ Set correspond to covering spaces $E \rightarrow X$, or families of sets continuously parametrised by X.
- Fact: ∞-functors P_X → Top correspond to fibrations E → X, or families of spaces continuously parametrised by X.
- Similarly: ∞ -functors $P_X \rightarrow \text{Sp}$ correspond to X-parametrised spectra.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- ► Given $A \stackrel{M}{\longleftrightarrow} B \stackrel{N}{\longleftrightarrow} C$ we put

 $M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn): A \nleftrightarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- **Problem:** generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- Given $A \stackrel{M}{\longleftrightarrow} B \stackrel{N}{\longleftrightarrow} C$ we put

 $M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn) : A \nleftrightarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- **Problem:** generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftarrow} B$.
- Given $A \stackrel{M}{\leftarrow} B \stackrel{N}{\leftarrow} C$ we put

 $M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn) : A \nleftrightarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- **Problem:** generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- Given $A \stackrel{M}{\leftrightarrow} B \stackrel{N}{\leftrightarrow} C$ we put

 $M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn)$: $A \leftarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- **Problem:** generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- Given $A \stackrel{M}{\leftarrow} B \stackrel{N}{\leftarrow} C$ we put

$$M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn)$$
: $A \nleftrightarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- ▶ Problem: generalise so that Bimod counts as an ∞-category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- Given $A \stackrel{M}{\leftarrow} B \stackrel{N}{\leftarrow} C$ we put

$$M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn)$$
: $A \nleftrightarrow C$

- ▶ This almost gives a category Bimod of rings and bimodules except that $M \circ N$ is really only defined by a universal property, and $L \circ (M \circ N)$ is only isomorphic (not equal) to $(L \circ M) \circ N$.
- Problem: generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given rings A and B, an (A, B)-bimodule is an abelian group M with amb defined for $(a, m, b) \in A \times M \times B$, subject to obvious axioms.
- Notation $A \stackrel{M}{\leftrightarrow} B$.
- Given $A \stackrel{M}{\leftarrow} B \stackrel{N}{\leftarrow} C$ we put

$$M \circ N = M \otimes_B N = (M \otimes_{\mathbb{Z}} N)/(mb \otimes n = m \otimes bn)$$
: $A \leftarrow C$

- This almost gives a category Bimod of rings and bimodules except that M ∘ N is really only defined by a universal property, and L ∘ (M ∘ N) is only isomorphic (not equal) to (L ∘ M) ∘ N.
- Problem: generalise so that Bimod counts as an ∞ -category.
- If we want to keep track of general homomorphisms of bimodules, that creates many extra difficulties. If we only keep track of isomorphisms of bimodules, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a cobordism from *N* to *M* is an (n + 1)-manifold *W* equipped with a specified homeomorphism $\partial W \simeq M \amalg N$.
- ▶ Notation $M \stackrel{W}{\leftrightarrow} N$.
- ► Given $L \stackrel{V}{\longleftrightarrow} M \stackrel{W}{\longleftrightarrow} N$ we put

 $V \circ W = V \cup_M W = \mathsf{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$

- This almost gives a category Cob_n of *n*-manifolds and cobordisms except that V ∘ W is really only defined by a universal property, and U ∘ (V ∘ W) is only homeomorphic (not equal) to (U ∘ V) ∘ W.
- **Problem**: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- ▶ Notation $M \stackrel{W}{\leftarrow} N$.
- Given $L \stackrel{V}{\leftarrow} M \stackrel{W}{\leftarrow} N$ we put

 $V \circ W = V \cup_M W = \mathsf{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$

- ▶ This almost gives a category Cob_n of *n*-manifolds and cobordisms except that $V \circ W$ is really only defined by a universal property, and $U \circ (V \circ W)$ is only homeomorphic (not equal) to $(U \circ V) \circ W$.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- Notation $M \stackrel{W}{\leftrightarrow} N$.
- Given $L \stackrel{V}{\leftarrow} M \stackrel{W}{\leftarrow} N$ we put

 $V \circ W = V \cup_M W = \mathsf{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$

- ▶ This almost gives a category Cob_n of *n*-manifolds and cobordisms except that $V \circ W$ is really only defined by a universal property, and $U \circ (V \circ W)$ is only homeomorphic (not equal) to $(U \circ V) \circ W$.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- ▶ Notation $M \stackrel{W}{\leftrightarrow} N$.
- Given $L \stackrel{V}{\leftarrow} M \stackrel{W}{\leftarrow} N$ we put

$$V \circ W = V \cup_M W = \text{pushout}(V \leftarrow M \rightarrow W): L \leftrightarrow N$$

- ▶ This almost gives a category Cob_n of *n*-manifolds and cobordisms except that $V \circ W$ is really only defined by a universal property, and $U \circ (V \circ W)$ is only homeomorphic (not equal) to $(U \circ V) \circ W$.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- ▶ Notation $M \stackrel{W}{\leftrightarrow} N$.
- Given $L \stackrel{V}{\longleftrightarrow} M \stackrel{W}{\longleftrightarrow} N$ we put

 $V \circ W = V \cup_M W = \text{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$

- This almost gives a category Cob_n of *n*-manifolds and cobordisms except that V ∘ W is really only defined by a universal property, and U ∘ (V ∘ W) is only homeomorphic (not equal) to (U ∘ V) ∘ W.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- ▶ Notation $M \stackrel{W}{\leftrightarrow} N$.
- Given $L \stackrel{V}{\leftarrow} M \stackrel{W}{\leftarrow} N$ we put

$$V \circ W = V \cup_M W = \text{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$$

- This almost gives a category Cob_n of *n*-manifolds and cobordisms except that V ∘ W is really only defined by a universal property, and U ∘ (V ∘ W) is only homeomorphic (not equal) to (U ∘ V) ∘ W.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- Given compact closed topological *n*-manifolds *M* and *N*, a *cobordism* from *N* to *M* is an (*n*+1)-manifold *W* equipped with a specified homeomorphism ∂*W* ≃ *M* II *N*.
- ▶ Notation $M \stackrel{W}{\leftrightarrow} N$.
- Given $L \stackrel{V}{\leftarrow} M \stackrel{W}{\leftarrow} N$ we put

$$V \circ W = V \cup_M W = \text{pushout}(V \leftarrow M \rightarrow W) \colon L \nleftrightarrow N$$

- This almost gives a category Cob_n of *n*-manifolds and cobordisms except that V ∘ W is really only defined by a universal property, and U ∘ (V ∘ W) is only homeomorphic (not equal) to (U ∘ V) ∘ W.
- Problem: generalise so that Cob_n counts as an ∞ -category.
- If we want to keep track of general maps between cobordisms, that creates many extra difficulties. If we only keep track of homeomorphisms between cobordisms, we get an ∞-category.

- There will be an ∞ -category Cat $_{\infty}$ of ∞ -categories (and functors and natural isomorphisms).
- ► This works like other ∞-categories, so we can consider (co)limits of diagrams of categories, systems of categories parametrised by a space, and so on. All of these things are much more difficult in traditional category theory.
- ▶ We can also consider the ∞-category Cat^{II}_∞ of ∞-categories that have finite colimits, and functors that preserve them. This is like an additive category.

- ► There will be an ∞-category Cat_∞ of ∞-categories (and functors and natural isomorphisms).
- ► This works like other ∞-categories, so we can consider (co)limits of diagrams of categories, systems of categories parametrised by a space, and so on. All of these things are much more difficult in traditional category theory.
- ▶ We can also consider the ∞-category Cat^{II}_∞ of ∞-categories that have finite colimits, and functors that preserve them. This is like an additive category.

- ▶ There will be an ∞ -category Cat_{∞} of ∞ -categories (and functors and natural isomorphisms).
- ► This works like other ∞-categories, so we can consider (co)limits of diagrams of categories, systems of categories parametrised by a space, and so on. All of these things are much more difficult in traditional category theory.
- We can also consider the ∞-category Cat^{II}_∞ of ∞-categories that have finite colimits, and functors that preserve them. This is like an additive category.

- There will be an ∞-category Cat_∞ of ∞-categories (and functors and natural isomorphisms).
- ► This works like other ∞-categories, so we can consider (co)limits of diagrams of categories, systems of categories parametrised by a space, and so on. All of these things are much more difficult in traditional category theory.
- ► We can also consider the ∞-category Cat^{II}_∞ of ∞-categories that have finite colimits, and functors that preserve them. This is like an additive category.

In the category of spaces it is natural to coherent diagrams like



is a homotopy from *rp* to *sq* and this is part of the data).

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ heq(f,q) = {(x, u) | u is a path in Y from f(x) to g(x)}.

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by background machinery.

In the category of spaces it is natural to coherent diagrams like



h is a homotopy from rp to sq (and this is part of the data).

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ heq(f,q) = {(x, u) | u is a path in Y from f(x) to g(x)}.

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by background machinery.

In the category of spaces it is natural to coherent diagrams like



h is a homotopy from rp to sq (and this is part of the data).

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ heq(f,q) = {(x, u) | u is a path in Y from f(x) to g(x)}.

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by background machinery.

In the category of spaces it is natural to coherent diagrams like



h is a homotopy from rp to sq (and this is part of the data).

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.

• Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ heq(f,q) = {(x, u) | u is a path in Y from f(x) to g(x)}.

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by background machinery.

In the category of spaces it is natural to coherent diagrams like



 $W \xrightarrow{p} X$ $\downarrow h \text{ is a homotopy from } rp \text{ to } sq$ $\downarrow h \text{ (and this is part of the data).}$

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- \blacktriangleright Given $f, g: X \rightarrow Y$ we have

$$eq(f,g) = \{x \in X \mid f(x) = g(x)\}$$

heq(f,q) = {(x, u) | u is a path in Y from f(x) to g(x)}.

- There is a more complicated story about homotopy (co)limits for
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like

In the category of spaces it is natural to coherent diagrams like



 $W \xrightarrow{p} X$ $\downarrow f \\ \downarrow r$ $\downarrow r$ $\downarrow f \\ \downarrow r$ $\downarrow r$

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ $heq(f, q) = \{(x, u) \mid u \text{ is a path in } Y \text{ from } f(x) \text{ to } g(x)\}.$

There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.

All this applies to any topological category, not just Top.

Problem: build a framework in which coherent diagrams behave like

In the category of spaces it is natural to coherent diagrams like



 $W \xrightarrow{p} X$ $\downarrow f \\ \downarrow r$ $\downarrow r$ $\downarrow f \\ \downarrow r$ $\downarrow r$

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ $heq(f, q) = \{(x, u) \mid u \text{ is a path in } Y \text{ from } f(x) \text{ to } g(x)\}.$

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like

In the category of spaces it is natural to coherent diagrams like



 $W \xrightarrow{p} X$ $\downarrow f \\ \downarrow r$ $\downarrow r$ $\downarrow f \\ \downarrow r$ $\downarrow r$

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ $heq(f, q) = \{(x, u) \mid u \text{ is a path in } Y \text{ from } f(x) \text{ to } g(x)\}.$

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by

In the category of spaces it is natural to coherent diagrams like



 $W \xrightarrow{p} X$ $\downarrow f \\ \downarrow r$ $\downarrow r$ $\downarrow f \\ \downarrow r$ $\downarrow r$

- There is a more complicated story about coherent diagrams of more general shape.
- In the category of spaces it is natural to consider homotopy limits.
- Given $f, g: X \to Y$ we have

 $eq(f,g) = \{x \in X \mid f(x) = g(x)\}$ $heq(f, q) = \{(x, u) \mid u \text{ is a path in } Y \text{ from } f(x) \text{ to } g(x)\}.$

- There is a more complicated story about homotopy (co)limits for (coherent) diagrams of more general shape.
- All this applies to any topological category, not just Top.
- Problem: build a framework in which coherent diagrams behave like ordinary commutative diagrams, and homotopy (co)limits behave like ordinary (co)limits. All differences should be handled magically by background machinery.

Other contexts

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

Other contexts

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

- ► There is a well-known analogy between homotopy theory of spaces and chain homotopy theory of chain complexes. There is a good ∞-categorical treatment of this.
- Part of the above story is the Dold-Kan Theorem: the category of nonnegative chain complexes is equivalent to the category of simplicial abelian groups. We can therefore develop homological algebra using simplicial objects instead of chain complexes.
- Simplicial objects also make sense without any group structure, so we can do nonlinear homological algebra a.k.a. homotopical algebra.
- Motivic homotopy theory is a kind of homotopical algebra for algebraic varieties, now much used in algebraic geometry. This also has a good ∞-categorical formulation.

- Δ is the simplicial category: objects are the sets [n] = {0,...,n}, and morphisms are nondecreasing functions.
- ► A simplicial set is a functor $X : \Delta^{op} \to Set$.
- Functoriality yields maps $d_i : X_n \to X_{n-1}$ and $s_j : X_n \to X_{n+1}$.
- We regard [n] as a category, with one morphism i → j if i ≤ j and none otherwise; then nondecreasing maps are the same as functors.

For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X : \Delta^{op} \to Set$.
- Functoriality yields maps $d_i : X_n \to X_{n-1}$ and $s_j : X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.

For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- Functoriality yields maps $d_i : X_n \to X_{n-1}$ and $s_j : X_n \to X_{n+1}$.
- We regard [n] as a category, with one morphism i → j if i ≤ j and none otherwise; then nondecreasing maps are the same as functors.

For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i : X_n \to X_{n-1}$ and $s_j : X_n \to X_{n+1}$.
- We regard [n] as a category, with one morphism i → j if i ≤ j and none otherwise; then nondecreasing maps are the same as functors.

For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.

For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- ▶ Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- ► A simplicial set is a functor $X : \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- **•** Thus: simplicial structure of NC determines the category C.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- ► A simplicial set is a functor $X : \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- ► A simplicial set is a functor $X : \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

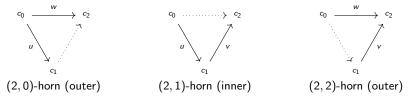
- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.

- ▶ Δ is the simplicial category: objects are the sets $[n] = \{0, ..., n\}$, and morphisms are nondecreasing functions.
- A simplicial set is a functor $X: \Delta^{op} \to Set$.
- ▶ Functoriality yields maps $d_i: X_n \to X_{n-1}$ and $s_j: X_n \to X_{n+1}$.
- ▶ We regard [n] as a category, with one morphism $i \rightarrow j$ if $i \leq j$ and none otherwise; then nondecreasing maps are the same as functors.
- For a category C we define the nerve NC by

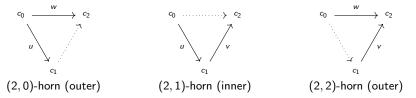
- *NC*₀ is the set of objects, *NC*₁ is the set of morphisms, *NC*₂ is the set of commuting triangles (which determines the composition rule).
- ▶ Thus: simplicial structure of *NC* determines the category *C*.
- Let X be a simplicial set.
 - X is the nerve of a groupoid iff it has unique fillers for all horns.
 - X is the nerve of a category iff it has unique fillers for all inner horns.
 - We say that X is an ∞ -groupoid if it has fillers for all horns.
 - We say that X is an ∞ -category if it has fillers for all inner horns.



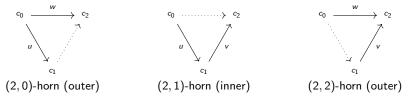
- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n</p>



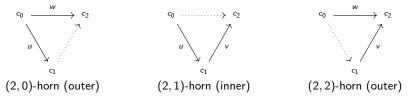
- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n</p>



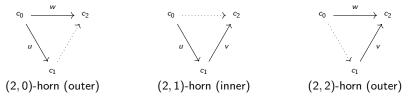
- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n</p>



- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n</p>



- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n</p>



- ▶ We can always fill a (2, 1)-horn using w = vu. If C is a groupoid we can fill a (2, 0)-horn with $v = wu^{-1}$, and fill a (2, 2)-horn with $u = v^{-1}w$.
- For general X: a (2,1)-horn is a pair $(u, v) \in X_1^2$ with $d_0(u) = d_1(v)$, and a filler is an element $x \in X_2$ with $d_0(x) = v$ and $d_2(x) = u$.
- The general definition of (n, k)-horns and fillers is combinatorially more complicated but in the same spirit.
- The (n, 0) and (n, n)-horns are outer; the (n, i)-horns are inner for 0 < i < n.</p>

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).

These are point, interval, triangle, tetrahedron,

For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.

For a map α : $[n] \to [m]$ in $\mathbf{\Delta}$ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- ▶ The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).

These are point, interval, triangle, tetrahedron, ...

- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- ▶ The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).

These are point, interval, triangle, tetrahedron, ...

For a space X we put
$$S_n X = \text{Top}(\Delta_n, X)$$
.

For a map α : $[n] \to [m]$ in $\mathbf{\Delta}$ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- ▶ The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

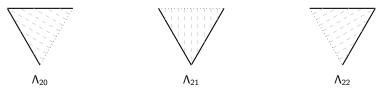
- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.



- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

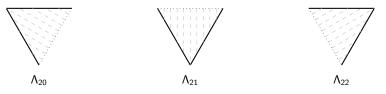
- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.

A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



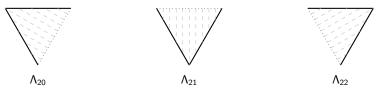
- The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.
- A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



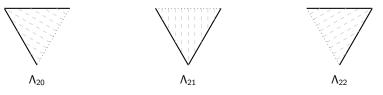
- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.
- A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



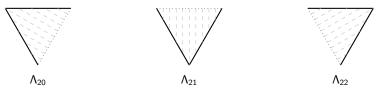
- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2 X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.
- A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



- ▶ The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2X$ filling u.
- ▶ A filler for a (2, 1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

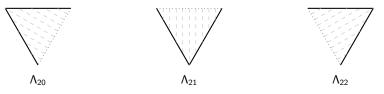
- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- ▶ For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.
- A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



- ▶ The dashed lines give a retraction r_{2i} : $\Delta_2 \rightarrow \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.

• This gives rise to an equivalence between spaces and ∞ -groupoids.

- ▶ Put $\Delta_n = \{(x_0, \ldots, x_n) \in [0, 1]^n \mid \sum_i x_i = 1\}$ (the geometric *n*-simplex).
- These are point, interval, triangle, tetrahedron, ...
- For a space X we put $S_n X = \text{Top}(\Delta_n, X)$.
- For a map α : $[n] \to [m]$ in Δ we have $\Delta_{\alpha} : \Delta_n \to \Delta_m$ and so $\alpha^* : S_m X \to S_n X$ given by $\alpha^*(u) = u \circ \Delta_{\alpha}$. This makes SX into a simplicial set.
- A (2, *i*)-horn in SX is a continuous map from the space $\Lambda_{2i} \subset \Delta_2$ to X.



- The dashed lines give a retraction $r_{2i}: \Delta_2 \to \Lambda_{2i}$ that is the identity on Λ_{2i} .
- For a horn $u: \Lambda_{2i} \to X$ we have $u \circ r_{2i}: \Delta_2 \to X$ i.e. $u \circ r_{2i} \in S_2X$ filling u.
- ▶ A filler for a (2,1)-horn is a justified path-composition.
- Every horn can be filled, so SX is an ∞ -groupoid.
- This gives rise to an equivalence between spaces and ∞ -groupoids.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

• When
$$k - i = 2$$
 that is the whole story.

- lf each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .
- When k i = 2 that is the whole story.
- lf each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

Coherent nerves

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .
- When k i = 2 that is the whole story.
- lf each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

Coherent nerves

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .
- When k i = 2 that is the whole story.
- lf each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .
- When k i = 2 that is the whole story.
- lf each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .
- When k i = 2 that is the whole story.
- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ► This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n C$ consists of objects $X_0, \ldots, X_n \in C$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to C(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ▶ This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- This can be souped up to define a space or ∞ -groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n C$ consists of objects $X_0, \ldots, X_n \in C$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to C(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ► This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Let C be a topological category, so every morphism set C(X, Y) has a topology and composition is continuous.
- As before: $N_0C = obj(C)$ and $N_1C = mor(C)$.
- ▶ An element of $N_n\mathcal{C}$ consists of objects $X_0, \ldots, X_n \in \mathcal{C}$, and morphisms $f_{ij}: X_i \to X_j$ for $i \leq j$, and continuous maps $h_{ij}: [0, 1]^{j-i-1} \to \mathcal{C}(X_i, X_j)$ for i < j subject to some conditions.
- To formulate these conditions efficiently, we need a detour into combinatorics.
- For i < j < k we can extract from h_{ik} a homotopy between $f_{jk} \circ f_{ij}$ and f_{ik} .

- If each C(X, Y) is discrete then each h_{ij} must be constant and we recover the nerve as defined previously.
- ► This coherent nerve construction converts topological categories to ∞-categories.
- For an ∞-category D we can make an ordinary category Ho(D): objects are 0-cells, morphisms are equivalence classes of 1-cells.
- ► This can be souped up to define a space or ∞-groupoid $\mathcal{D}(X, Y)$ with $Ho(\mathcal{D})(X, Y) = \pi_0(\mathcal{D}(X, Y))$. However, there are some subtleties here.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \Delta([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \Delta([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with (Δ_n)_k = Δ([k], [n]), and (∂Δ_n)_k is the subset of non-surjective maps.)
- A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- ln an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with (Δ_n)_k = Δ([k], [n]), and (∂Δ_n)_k is the subset of non-surjective maps.)
- A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- ln an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \mathbf{\Delta}([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \mathbf{\Delta}([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- ▶ A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \mathbf{\Delta}([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- ▶ A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \mathbf{\Delta}([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- ▶ A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.

- Say that a simplicial set X is an *acyclic Kan complex* if every $u: \partial \Delta_n \to X$ can be extended to give a morphism $\Delta_n \to X$.
- (Here Δ_n is the combinatorial simplex, i.e. the simplicial set with $(\Delta_n)_k = \mathbf{\Delta}([k], [n])$, and $(\partial \Delta_n)_k$ is the subset of non-surjective maps.)
- ▶ A standard fact: X is an acyclic Kan complex iff it is an ∞-groupoid and the corresponding space is contractible.
- In an ordinary category C: we say that an object T is terminal iff C(X, T) is a single point for all X.
- In an ∞-category C: we say that T is terminal iff C(X, T) is a contractible ∞-groupoid for all X.
- More generally: any definition in category theory involving a unique choice is replaced by a condition involving a contractible space of choices.
- After understanding this principle, we can formulate appropriate definitions of limits, colimits and so on.
- ► If C arises as the coherent nerve of a topological category, then these ∞-categorical (co)limits are essentially the same as older notions of homotopy (co)limits.